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\*We reserve the right to change the information in this catalogue without prior notice



### **Delta High-Speed Motion Control System**





### Introduction to DMCNET\*\*

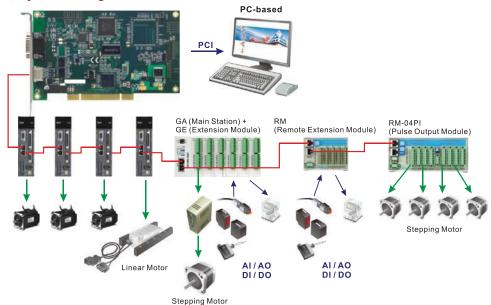
In response to positive market feedback on the ASDA-A2 series AC servo motors and drives, Delta has launched its brand-new, high-speed and cost-effective PCI-DMC-A01 motion control card which provides high performance and extended functions for multi-axis motion control. With the aid of the high precision and high functioning ASDA-A2-F series that features a 20-bit level resolution encoder, Delta provides an optimum motion control system for meeting the demanding requirements of a wide variety of industry applications.

Delta's new PMCNET motion control card facilitates motion control via communication. It is easy to set up, has good extension abilities and no extra I/O card is required. The commands are delivered with no pulse delay. The synchronization it achieves enhances the stability and efficiency of the system.

EMENET\* is a high speed and real time communication system, capable of controlling up to 12 axes of servo system units within 1ms simultaneously. It can accept double precision floating point values 64-bits wide and provide up to 1,280,000 pulse/rev resolution so the servo system can make accurate calculations and provide operation flexibility. 35 homing modes are provided. 12 servo system units or 4 groups, 3-axis helical and linear interpolation or 6 groups, 2-axis linear and arc interpolation can be implemented synchronously. It also supports absolute commands, incremental commands, T-curve / S-curve velocity profiles, built-in position, speed and torque control modes for different uses. Simply by connecting the EMENET\* to servo motors, linear motors, digital inputs and outputs (DI/DO), analog inputs and outputs (AI/AO) and other control devices such as stepping motors and manual pulse generators (MPG), enabling fast and cost-effective communication and control is easy.

**EMENET** is the best integrated platform for multi-axis and synchronous motion control in a wide range of machine tools and industrial applications. It is also the ultimate solution that provides effortless wiring, enhanced stability, flexible extension capabilities and versatile operation for industry upgrading and adding value to products.

### System Configuration



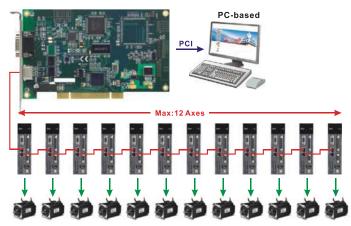
### **Features**

### **High Integrated Capability**

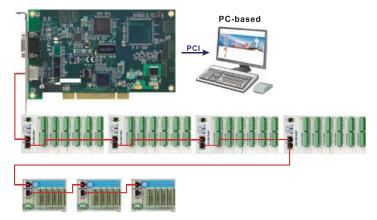
- ▶ With DELECTIVE networking structure, multiple control devices such as servo motors, remote digital and analog modules, stepping motors, elevator door control motors (VFD-DD series), and linear motors can be easily and quickly connected.
- ▶ Up to 20Mbps communication bandwidth is provided. Maximum distance for communication is 30m (98.4ft.)

### ● Pure Motion Structure:

Data of 12 servo system units can be transferred within 1ms simultaneously.



### Pure I/O Structure:

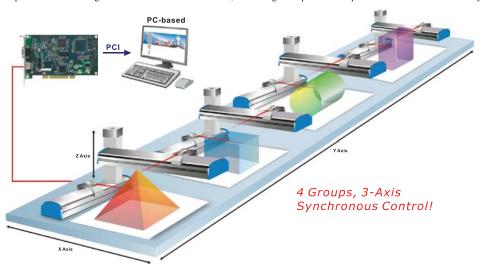


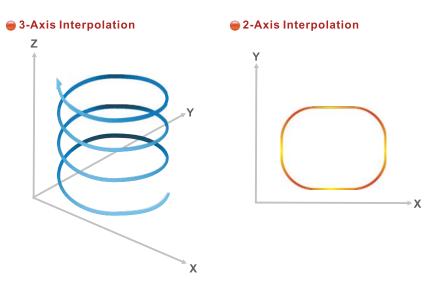


### **Synchronous Control**

Simultaneous 3-axis linear interpolation, 2-axis are interpolation, 3-axis helical interpolation and continuous interpolation can be implemented.

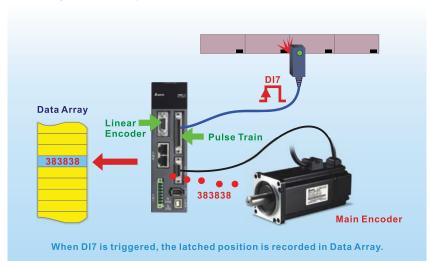
ability to control 12 servo system units or 4 groups, 3-axis interpolation algorithms synchronously. It is also capable of transferring the data of 12 servo motor units, or 768 digital inputs and outputs within 1ms simultaneously.

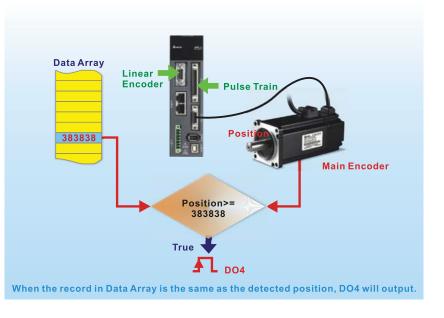




### Capture (Position Latch) and Compare (Position Detection) Functions

The Capture and Compare functions can be applied to latch and detect a reference position which can be signals from the main encoder, linear encoder, or pulse train. It is possible to record 800 items with the maximum length of the data array.

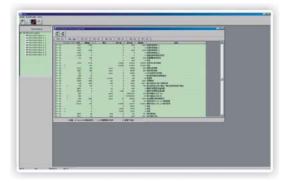




# Delta Motion Control Network

### **EzDMC Software**

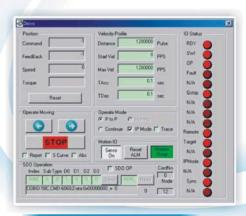
EzDMC software makes editing easier than ever and facilitates program development. Even users who use the Delta DMCNET motion control card for the first time are able to utilize the functions of this motion control card.



### **User-friendly Operator Interface**

In EzDMC, a familiar user interface, clear images and easy-to-use dialog boxes helps users create and edit programs easily and quickly. Many example programs are contained on the CD packaged with the box. New programs are easily created just using the example programs.

Control gains can be automatically tuned to the optimum values via the servo tuning function provided in EzDMC.



### **Independent Control Unit**

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When DMCNET serial communication is setup, users can read and write into the connecting servo drives and control the system from a PC.



### **Multi-axis Motion Control**

In EzDMC, there are many example programs available for linear, arc and helical interpolation. Users can choose different control modes such as Linear2, Linear3, Heli, Circle, Circle2 and Circle3 to easily edit and program for multi-axis control.



### Real Time Response

Monitoring and displaying the status of the connected servo drives through EzDMC is easy and simple.

10 Status

# Delta Motion Control Network

### **Part Names and Functions**

### • LED Display / Operation Panel / Charge LED

Operation

Charge LED

LED

Display

AC 220V

■ LED Display
The 5 digit, 7 segment LED displays the servo status or fault codes.

 Operation Panel Function keys used to perform status display, monitor and diagnostic, function and parameter setting.
 Function Keys:

MODE: Press this key to select/ change mode

SHIFT: Press this key to shift cursor to the left

UP: Press this key to increase values on the display DOWN: Press this key to decrease values on the display SET: Press this key to store data

■ Charge LED

A lit LED indicates that either power is connected to the servo drive or a residual charge is present in the drive's internal power components.

### • Full-Closed Control Interface

■ Used to connect linear scale and encoder for controlling A, B, Z phase signals.

### • I/O Interface -

■ Used to connect Delta's DVP series PLC or other external controllers for controlling I/O signals.

### • High-speed Communication Port

- Used to connect CANopen networks.
- 1-in/1-out communication ports offer easy serial connection.
- CANbus interface, supporting motion modes for CANopen DS402 implementation.

### Motor Encoder Interface

■ Used to connect the encoder of the servo motor

### Serial Communication Port

■ Used to connect PLC, HMI, and other controllers for RS-485 / RS-232 serial communication.

#### USB Connection Port

- Used to connect personal computers or notebooks.
- Ver 1.1 USB is equipped as standard.
- Direct connectivity to personal computers or notebooks, capable of accessing data through ASDA-Soft configuration software.
- Monitor speed upon software is up to 1Mbps.



- Internal & External Regenerative Resistor Terminal
- 1. When using an external resistor, connect it to P  $\oplus$  and C , and ensure an open circuit between P  $\oplus$  and D.
- 2. When using an internal resistor, ensure the circuit is closed between  $P \oplus$  and D, and the circuit is open between  $P \oplus$  and C. (Note: Please refer to the table of regenerative resistor specifications for the models with a built-in regenerative resistor.)
  - 3. When using an external braking unit, connect it to P⊕ and ⊖, and ensure an open circuit between P⊕ and D, and P⊕ and C
  - Control Circuit Terminal (L1c, L2c or DC24V, DC0V)
    220V Series: L1c, L2c are used to connect
    200~230Vac, 50/60Hz single-phase or
    three-phase power supply.
    400V Series: DC24V, DC0V are used to
    connect 24Vdc ±10% power supply.
  - Main Circuit Terminal (R, S, T)
    220V Series: Used to connect 200~230Vac,
    50/60Hz commercial power supply.
    400V Series: Used to connect 380~480Vac,
    50/60Hz commercial power supply.
  - When using an external braking unit, connect it to  $P \oplus$  and  $\ominus$ .

### • Servo Motor Output (U, V, W)

■ Used to connect servo motor. Never connect the output terminal to main circuit power as the AC drive may be damaged beyond repair if incorrect cables are connected to the output terminals.

### Ground Terminal

■ Used to connect grounding wire of power supply and servo motor.

#### Heatsink

■ Used to secure servo drive and for heat dissipation.

Please note:



## **PCI-DMC-A01 Specifications**

Items	PCI-DMC-A01			
Supporting Servo Drive	Delta ASDA-A2-F series servo drives			
Homing Mode	35 kinds of homing modes (set by parameters via DMCNET)			
Velocity Profile	T-curve, S-curve			
Interpolation Mode	Linear, Arc and Continuous			
Number of Rings	1 Ring			
Supporting Tool Language	VB, VC, BCB, DELPHI, C#, VB.NET			
Communication Cable	Category 5e STP Ethernet cable (24AWG/4Pairs)			
Communication Distance	Max. 30m (12 slave module)			
Communication Interface	half duplex RS-485 with transformer isolation			
PCI Specifications	ver.2.2, supports 32-bit, 3.3V/5VDC operation			
Power Consumption	+5V DC at 0.5A typical			
Noise Tolerance Threshold	Withstand (Peak) voltage: 1500VAC(Primary-secondary); 1500VAC(Primary-PE) ESD (IEC 61131-2, IEC 61000-4-2): 8KV Air Discharge EFT (IEC 61131-2, IEC 61000-4-4): Power Line: 2KV, Communication I/O: 1KV RS (IEC 61131-2, IEC 61000-4-3): 26MHz ~ 1GHz, 10V/m			
Environment	Operating Temperature: 0°C ~ 50°C; Storage Temperature: -20°C ~ 70°C			
	Humidity: 5 ~ 95% (non-condensing)			

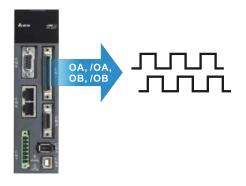
### **Dimensions**



## **General Signals of Connector CN1**

Sig	ınal	Pin No	Description		
Analog Monitor Output	MON1 MON2	16 15	Monitor operation status: Motor characteristics such as speed and current can be represented by analog voltages. The servo drive provides two channels which can be configured with the parameter P0-03 to output the desired characteristics. Output voltage is reference to the power ground.		
	OA /OA	21 22			
Position Pulse	Pulse /OB 23 a	Encoder signal output A, B, Z (Line-driver output). The motor encoder signals are available through these terminals.			
Output	OZ /OZ	50 24			
	ocz	48	Encoder signal output Z (Open-collector output).		
	VDD	17	VDD is the +24V source voltage provided by the drive. Maximum permissible current 500mA.		
Power	COM+ 45 COM- 47 Power 49		COM+ is the common voltage rail of the Digital Input (DI) and Digital Output (DO) signals. When using VDD, VDD should be connected to COM+. If not using VDD, users should add external applied power (+12V to +24V). The positive end of this applied power should be connected to COM+ and the negative end of this applied power should be connected to COM		
vcc	20	VCC is a +12V power rail provided by the drive. It is used for providing simple analog commands (analog speed or analog torque command). Maximum permissible current 100mA.			
	GND	12,13, 19,44	The polarity of VCC is with respect to Ground (GND).		
Other	NC	14	The terminal marked "NC" must be left unconnected (No Connection). The NC terminal is used within the servo drive. Any outside connection to the NC terminal will result in damage to the drive and void the warranty!		

## **Monitoring Signals**

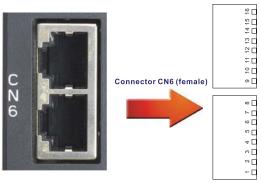




### Connector CN6 for DMCNET™ Communication

The connector CN6 accepts RJ45 connectors and isolated cables for connecting Delta's motion control card directly to servo drives and host controllers (external controllers). With this connector CN6, servo drives can connect to a CMCNET\* high-speed motion control system and perform position, speed and torque control. It also can be used to read and monitor the status of the servo drives through CMCNET\* communication.

The station numbers of **DMCNET** communication are the same as RS-232 and RS-485 communication and all are determined by parameter P3-00. The transmission speed can reach up to 20Mbps. There are two communication ports for connector CN6, one is for transmission and the other is for receiving, which is convenient for direct connection of more than one servo drive in serial. Be sure to connect a  $120\Omega$  termination resistor to the last connected servo drive.



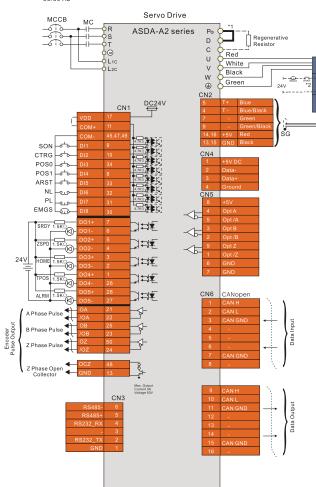
Pin No	Signal Name	Description
1, 9	DMCNET_1A	DMCNET Channel 1 bus line (+)
2, 10	DMCNET_1B	DMCNET Channel 1 bus line (-)
3, 11	DMCNET_2A	DMCNET Channel 2 bus line (+)
4, 12		Reserved
5, 13		Reserved
6, 14	DMCNET_2B	DMCNET Channel 2 bus line (-)
7, 15		Reserved
8, 16		Reserved

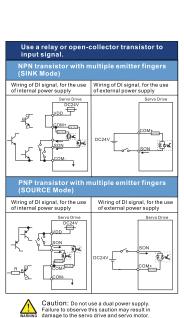
<sup>#</sup> Connecting method of termination resistor: Two  $120\Omega$  termination resistors are required. One is connected between DMCNET 1A and DMCNET 1B and the other is connected between DMCNET 2A and DMCNET 2B.



# Standard Connection Examples for Delta Motion Control Network Communication (ASDA-A2-F Series)

AC 200/230V Single-phase or Three-phase 50/60 Hz





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- Please refer to wiring diagrams of SINK / SOURCE mode.
- 2) 400W and below drives do not provide a built-in regenerative re
- The brake oil has no polarity.
   USB connector is for connecting to personal computers or notebooks.



## **ASDA-A2-F Servo Drive Specifications**

			100W	200W	400W	750W	1kW	1.5kW	2kW	3kW	4.5kW	5.5kW	7.5kW
	ASDA-A2 Serie	es	01	02	04	07	10	15	20	30	45	55	75
ver ply	Phase / Voltage					55VAC, 5 55VAC, 5			٦	Three-ph	ase: 170 50/6	~255VAC 60Hz ±5%	
Power supply	Continuous Output	Current	0.9 Arms	1.55 Arms	2.6 Arms	5.1 Arms	7.3 Arms	8.3 Arms	13.4 Arms	19.4 Arms	32.5 Arms	40 Arms	47.5 Arms
	Cooling System		Natura	al Air Circ	ulation				Fan C	Cooling			
	Encoder Resolutio Feedback Resoluti						20-bit	(1280000	p/rev)				
	Control of Main Cir	cuit			SVPW	M (Space	e Vector	Pulse Wi	dth Mod	ulation)	Control		
	Tuning Modes					High-sp	eed ser	ial commu	ınicatior	n control			
	Dynamic Brake			None				Buil	t-in			Exte	rnal
٥	Command Source						Со	mmunicat	tion				
100	Smoothing Strateg	у				L	.ow-pas	s and P-ci	urve filte	er			
i i	Electronic Gear			Electr	onic gea	r N/M mul	tiple N:	1~32767,	M: 1:32	767 (1/5	50 <n m<<="" td=""><td>25600)</td><td></td></n>	25600)	
Position Control Mode	Torque Limit Opera	ition					Set	oy parame	eters				
- 3	Feed Forward Com	pensation					Set	oy parame	eters				
	Speed Control Ran	ge <sup>*1</sup>						1:5000					
de	Command Source					Co	mmunicat	tion					
ž	Smoothing Strateg	Low-pass and S-curve filter											
<u> </u>	Torque Limit Opera	Torque Limit Operation			Set by parameters or via analog input								
Speed Control Mode	Frequency Respon Characteristic	se	Maximum 1kHz										
eed	*2		0.01% or less at 0 to 100% load fluctuation										
Spe	Speed Accuracy*2 (at rated rotation sp	peed)	0.01% or less at $\pm$ 10% power fluctuation										
	,	,	0.01% or less at 0°C to 50 °C ambient temperature fluctuation										
ode	Command Source		Communication										
Torque Control Mode	Smoothing Strateg	у	Low-pass filter										
Conf	Speed Limit Opera	tion	Set by parameters										
Inp		Inputs	control Motor's Speed PT / PF Refere Move to Event t	, Comma stop, Spe / Torque R commar nce "Home" o "Home" rigger PF nhibit inp	nd trigge ed positi mode sw nd switch ne" sense Electro R comma ut.	ered, Spe on select itching, T iing, Eme or, Forwa nic Cam ( nd, Elect	ed/Torqi ion, Pos orque / I rgency : rd / Rev (E-Cam) ronic ge	ear, Zero ue limit er ition / Spe Position n stop, Forv erse oper ı, Forward ar ratio (N	nabled, Feed mode node sw vard / Re ation tor I / Rever lumerate	Position le switch itching, everse in que limi se JOG or) selec	command ing, hibit limit i, nput, tion and	selectio	n,
lnı	Digital nputs/Outputs		The above digital inputs are not designed for DMCNET communication mode. If using the above digital inputs in DMCNET communication mode, it is recommended to write into digital inputs via DMCNET communication. Only emergency stop, forward / reverse inhibit limit, reference "Home" sensor can be used in DMCNET communication mode.							digital			
				Е	ncoder s	ignal outp	out (A, B	, Z Line D	river an	d Z Oper	Collecto	r)	
		At Torq Homing Positio comple	ues limit, g comple n comma ted, Cap	Servo a ted, Outp nd overf ture ope	larm (Ser out overlo low, Forw	vo fault ad warn ard / Re npleted	Speed rea ) activated ing, Serveverse sof output., N	d, Electr o warnin tware lir	omagne ng activa nit, Inter	tic brake ted, nal positi	control, on comm	and	

	AODA AO O	100W	200W	400W	750W	1kW	1.5kW	2kW	3kW	4.5kW	5.5kW	7.5kW
	ASDA-A2 Series	01	02	04	07	10	15	20	30	45	55	75
	Analog Monitor Output	Monitor signal can be set by parameters (Output voltage range: $\pm$ 8V)										
	Protective Functions	Overs Adjust Position	peed, Ab ment err on exces oower ph	normal p or, Emer sive devi	ulse cont gency sto ation of fi Serial co	rol comr p activa ull-close	, Motor or mand, Ex ted, Reve d control cation tim	cessive erse/ For loop, Se	deviation ward lim	n, Encode it switch munication	er error, error, on error,	
	Communication Interface				RS-23	32/RS-4	85/ <b>DMC</b>	ET"/USI	3			
	Installation Site	Indoor location (free from direct sunlight), no corrosive liquid and gas (far away from oil mist, flammable gas, dust)										
	Altitude	Altitude 1000m or lower above sea level										
	Atmospheric Pressure	86kPa ~ 106kPa										
	Operating Temperature	0°0	C ~ 55°C	(If opera	ating tem	perature	is above	45°C, fo	rced coo	ling will b	e require	ed)
Ħ	Storage Temperature		-20°C ~ 65°C (-4°F to 149°F)									
E E	Humidity				(	to 90%	(non-cor	densing	)			
Environment	Vibration		:	9.80665r	n/s² (1G)	less tha	n 20Hz, 5	.88m/ s²	(0.6G) 2	0 to 50H	z	
Ē	IP Rating						IP20					
ш	Power System					Т	N Systen	1 <sup>'3</sup>				
	Approvals				C	EN 6180	0-5-1, UL	. 508C, C	K Mark			

- \*1 Rated rotation speed: When full load, speed ratio is defined as the minimum speed (the motor will not pause).
- 2 When command is rated rotation speed, the speed fluctuation rate is defined as:

  (Empty load rotation speed Full load rotation speed) / Rated rotation speed

  3 TN system: A power distribution system having one point directly earthed, the exposed conductive parts of the installation being connected to that point by a protective earth conductor.

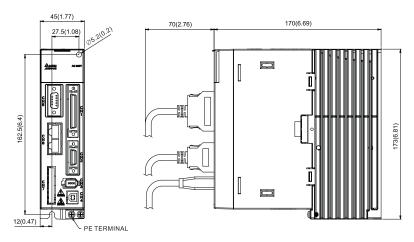




### **ASDA-A2-F Servo Drive Dimensions**

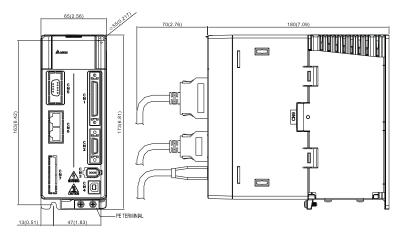
ASD-A2-0121-F; ASD-A2-0221-F; ASD-A2-0421-F (100W ~ 400W)

Weight 1.5 (3.3)



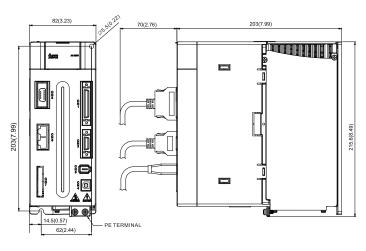
ASD-A2-0721-F; ASD-A2-1021-F; ASD-A2-1521-F (750W ~ 1.5kW)

Weight 2.0 (4.4)



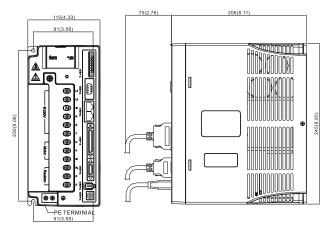
ASD-A2-2023-F; ASD-A2-3023-F (2kW ~ 3kW)





ASD-A2-4523-F (4.5kW)

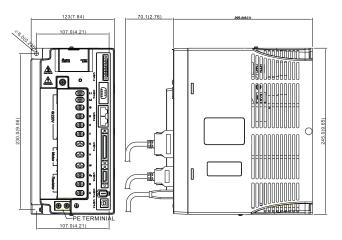
Weight 4.4 (9.7)



### **ASDA-A2-F Servo Drive Dimensions**

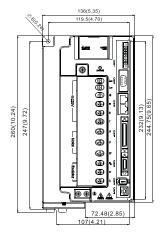
ASD-A2-5523-F (5.5kW)

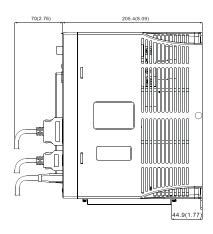




### ASD-A2-7523-F (7.5kW)

5.9 (13.0)





### **Optional Accessories of ASDA-A2-F Servo Drives**

### **▶ Quick Connectors**

- Used for 100W to 300W servo drives
- One operating lever is provided for wire to terminal block insertion



#### ▶ Power Cables

- 3m and 5m standard cables are available
- Customized service is offered to meet the needs of customers
- Two types are selectable:



### **▶** Encoder Cables

- 3m and 5m standard cables are available
- Customized service is offered to meet the needs of customers



### **▶ DMCNET Accessories**

■ DMCNET communication cable is provided. Standard cable length is 0.5m and 1m.



### ► Regenerative Resistors

 $\blacksquare$  400W, 40 $\Omega$  and 1kW, 20 $\Omega$ two kinds of specifications are available.





## Extension Modules on Delta Motion Control Network

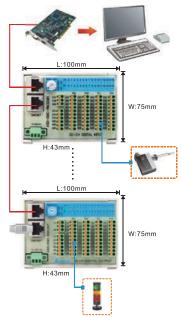
### **Remote Extension Modules**

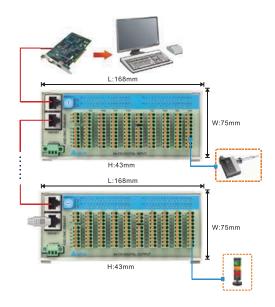
- ► ASD-DMC-RM32MN/ASD-DMC-RM32NT
- ► ASD-DMC-RM64MN/ASD-DMC-RM64NT

### Electrical Specifications

Item	RM32MN/RM64MN	RM32NT/RM64NT			
Circuit Type	Single	Transistor			
Signal Type	SINK / SOURCE	SINK			
Power Supply Voltage	24VDC (5mA)	24VDC (0.1A / 1point)			
Response Time / Work Frequency	0 ~ 3ms (adjustable)	1KHz			
Active Level (OFF > ON)	>16.5VDC	20us			
Active Level (ON > OFF)	<8VDC	30us			
Noise Immunity	ESD (IEC 61131-2, IEC 61000-4-2): 8KV Air Discharge EFT (IEC 61131-2, IEC 61000-4-4): Power Line: 2KV, Communication I/O: 1F RS (IEC 61131-2, IEC 61000-4-3): 80MHz ~ 1GHz, 10V/m				
Operating/Storage Environment	Operation: 0°C~ 55°C; Storage: -20°C ~ 70°C				

### Installation and Wiring





### ► ASD-DMC-RM04PI

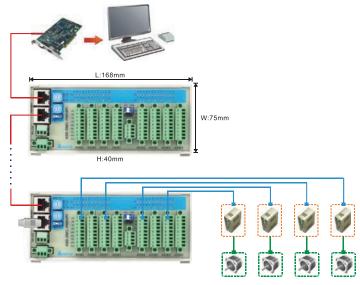
### Electrical Specifications

ASD-DMC-RM04PI					
Item	Input (QA,QB,QZ,DI1,DI2)				
Circuit Type	Single				
Signal Type	SINK				
Power Supply Voltage	5VDC				
Work Frequency	QA, QB, QZ : 200KHz (5mA / 1point) DI1, DI2 : 1KHz (5mA / 1point)				
Noise Immunity	ESD (IEC 61131-2, IEC 61000-4-2): 8KV Air Discharge EFT (IEC 61131-2, IEC 61000-4-4): Power Line: 2KV, Communication I/O: 1KV RS (IEC 61131-2, IEC 61000-4-3): 80MHz ~ 1GHz, 10V/m				
Operating/ Storage Environment	Operation: 0°C~ 50°C; Storage: -20°C ~ 70°C				

	ASD-DMC-RM04PI				
Item	Input (MEL,PEL,ORG,SLD)	Output (MEL,PEL,ORG,SLD)			
Circuit Type	Single	Transistor			
Signal Type	SINK / SOURCE	SINK			
Power Supply Voltage	24VDC (5mA)	5~24VDC (30mA / 1point)			
Response Time/ Work Frequency	1ms	CW, CCW : 200KHz DO1, DO2 : 1KHz			
Active Level (OFF > ON)	>16.5VDC				
Active Level (ON > OFF)	<8VDC				
Noise Immunity	ESD (IEC 61131-2, IEC 68KV Air Discharge EFT (IEC 61131-2, IEC 62KV, Communication I/RS (IEC 61131-2, IEC 6180MHz ~ 1GHz, 10V/m	1000-4-4): Power Line: O: 1KV			
Operating/ Storage Environment	Operation: 0°C~ 50°C; Storage: -20°C ~ 70°C				

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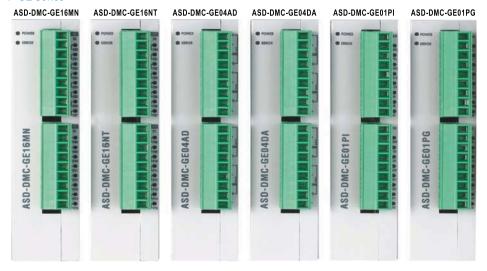
### Installation and Wiring



# Delta Motion Control Network

### Station Extension Modules (Available soon)

### ► GE Series



### Gateway Main Station (Available soon)

### ► GA Series



### ► ASD-DMC-GA01 Switch Settings

	ADDR1		
E	Pin	Description	Note
ADD	1~ 12	Start Node Address	Start Station
OMESS T	ADDR2		
ON NOON	Pin	Description	Note
ADDR1 & ADDR2	1~ 12	End Node Address	End Station
	There is no commu	nication when the value is tuned to	0 and 13~15.

There is no communication when the value is tuned to 0 and 13~15. If ADDR1 is set to 1 and ADDR2 is set to 2, it indicates that the extension modules have occupied two stations.

## **Ordering Information**

PCI-DMC-A01	PCI-DMC-A01 High-speed Motion Control Card
Gateway Main St	ation
ASD-DMC-GA01	ASD-DMC-GA01 Gateway Main Station (Available soon)
Station Extensio	n Modules
ASD-DMC-GE16MN	16 Digital Inputs (NPN/PNP) (Available soon)
ASD-DMC-GE16NT	16 Digital Outputs (Transistor Output) (Available soon)
ASD-DMC-GE04AD	4 Analog Inputs (Available soon)
ASD-DMC-GE04DA	4 Analog Outputs (Available soon)
ASD-DMC-GE01PI	1 Pulse Output (Available soon)
ASD-DMC-GE01PG	1 Manual Pulse Generator (MPG) (Available soon)
Remote Extensio	n Madulas
ASD-DMC-RM32MN	32 Digital Inputs (NPN/PNP)
ASD-DMC-RM64MN	64 Digital Inputs (NPN/PNP) + Manual Pulse Generator (MPG)
ASD-DMC-RM32NT	32 Digital Outputs (Transistor Output)
ASD-DMC-RM64NT	64 Digital Outputs (Transistor Output)
ASD-DMC-RM04N1	4 Pulse Outputs
	41 dioo Gutputo
AC Servo Drives	
ASD-A2-0121-F	A2 100W Servo Drive for PMCNET*
ASD-A2-0221-F	A2 200W Servo Drive for Complete State State Complete State
ASD-A2-0421-F	A2 400W Servo Drive for COMMENT'S
ASD-A2-0721-F	A2 750W Servo Drive for PMCNET"
ASD-A2-1021-F	A2 1.0kW Servo Drive for CMCNET**
ASD-A2-1521-F	A2 1.5kW Servo Drive for DMCNET**
ASD-A2-2023-F	A2 2.0kW Servo Drive for PMCNET
ASD-A2-3023-F	A2 3.0kW Servo Drive for PMCNET*
ASD-A2-4523-F	A2 4.5kW Servo Drive for PMCNET
ASD-A2-5523-F	A2 5.5kW Servo Drive for PMCNET

For ordering information of AC servo motors and accessories, please refer to the ASDA-A2 series catalogue.

