



Automation for a Changing World

Delta AC Servo Drive ASDA-A2-E Series



EtherCAT®

www.deltaww.com

 **DELTA**
Smarter. Greener. Together.

Introduction

Delta's ASDA-A2-E, an advanced AC Servo Drive with an EtherCAT communication interface, complies with IEC61158 and IEC61800-7 and follows in the footsteps of the successful ASDA-A2 series. This advanced A2-E supports all the modes of the CoE device profile based on CiA402 and all command types of EtherCAT; features built-in Safe Torque Off (STO) function which prevents torque energy from continuing to act upon a motor and avoid accidents. In addition, A2-E offers extension digital input port for a wide range of machinery automation fields. This series cover power range from 400W to 7.5kW for 400V and 100W to 3kW for 220V.

ASDA-A2-E Series is your ideal servo drive to achieve high speed multi-axis synchronization applications.

Features

- Pass EtherCAT conformance test by EtherCAT Technology Group (ETG)
- Integrated Safe Torque Off (STO) safety function according to the following standards:
 - IEC EN 61508 (SIL 2)
 - IEC 62016 (SIL 2)
 - ISO 13849-1 (Cat.3 PL=d)
- Supports full closed-loop control (use output signals from sensors)
- Supports absolute type and incremental type servo motors
- Supports high speed position latch (Capture) function
 - Enabled with dedicated Digital Input (DI) on CN7 or the external encoder

Applications



Specifications of ASDA-A2-E_220V Series

ASDA-A2-E Series		100W 01	200W 02	400W 04	750W 07	1 kW 10	1.5 kW 15	2 kW 20	3 kW 30											
Power Supply	Phase / Voltage	Three-phase / Single-phase 220V _{AC}						Three-phase 220V _{AC}												
	Permissible Voltage Range	Three-phase / Single-phase 200 ~ 230V _{AC} , -15%~10%						Three-phase 200 ~ 230V _{AC} , -15% ~ 10%												
	Input Current (3 PH) Unit: Arms	0.39	1.11	1.86	3.66	4.68	5.9	8.76	9.83											
	Input Current (1 PH) Unit: Arms	0.69	1.92	3.22	6.78	8.88	10.3	-	-											
Continuous Output Current	Unit: Arms	0.9	1.55	2.6	5.1	7.3	8.3	13.4	19.4											
Cooling Method		Natural Air Circulation			Fan Cooling															
Encoder Resolution (Servo Drive Resolution)		Incremental type: 20-bit ; Absolute type: 17-bit																		
Control of Main Circuit		SVPWM (Space Vector Pulse Width Modulation) Control																		
Tuning Modes		Auto / Manual																		
Dynamic Brake		no		Built-in																
Position	Command Source	DS402 object																		
Control	Smoothing Strategy	Low-pass and P-curve filter																		
Mode	Electronic Gear	Electronic gear N/M multiple N: 1 ~ 32767, M: 1 : 32767 (1/50 < N/M < 25600)																		
(CSP)	Torque Limit Operation	DS402 object																		
	Feed Forward Compensation	Internal parameters																		
Speed	Speed Control Range ¹	1:5000						1:3000												
Control	Command Source External Analog Signal	DS402 object																		
Mode	Smoothing Strategy	Low-pass and S-curve filter																		
(CSV)	Torque Limit Operation	Set by parameters																		
	Frequency Response Characteristic	Maximum 1 kHz																		
	Speed Accuracy (at rated rotation speed) ²	0.01 % or less at 0 to 100 % load fluctuation 0.01 % or less at 0°C to 50°C ambient temperature fluctuation																		
	Feed Forward Compensation	0.01 % or less at ±10 % power fluctuation																		
Torque Control Mode	Command Source	DS402 object																		
(CST)	Smoothing Strategy	Low-pass filter																		
	Speed Limit Operation	DS402 object																		
Digital Inputs/Outputs	Inputs	Servo on, Reset, Gain switching, Zero speed CLAMP, Command input reverse control, Command triggered, Speed/Torque limit enabled, Position command selection, Motor stop, Speed position selection, Position / Speed mode switching, Speed / Torque mode switching, Torque / Position mode switching, Emergency stop, Forward / Reverse inhibit limit, Reference "Home" sensor, Forward / Reverse operation torque limit, Move to "Home", Electronic Cam (E-Cam), Forward / Reverse JOG input, Event trigger PR command, Electronic gear ratio (Numerator) selection Encoder signal output (A, B, Z Line Driver and Z Open Collector)																		
	Outputs	Servo ready, Servo on, At Zero speed, At Speed reached, At Positioning completed, At Torques limit, Servo alarm (Servo fault) activated, Electromagnetic brake control, Homing completed, Output overload warning, Servo warning activated, Position command overflow, Forward / Reverse software limit, Internal position command completed, Capture operation completed output., Motion control completed output., Master position of E-Cam (Electronic Cam)																		
	Protective Functions	Overcurrent, Overvoltage, Undervoltage, Motor overheated, Regeneration error, Overload, Overspeed, Abnormal pulse control command, Excessive deviation, Encoder error, Adjustment error, Emergency stop activated, Reverse/ Forward limit switch error, Position excessive deviation of full-close control loop, Serial communication error, Input power phase loss, Serial communication time out, short circuit protection of U, V, W, and CN1, CN2, CN3 terminals																		
Communication Interface		USB / EtherCAT																		
Environment	Installation Site	Indoor location (free from direct sunlight), no corrosive liquid and gas (far away from oil mist, flammable gas, dust)																		
	Altitude	Altitude 1000 m or lower above sea level																		
	Atmospheric Pressure	86kPa ~ 106kPa																		
	Operating Temperature	0°C ~ 55°C (If operating temperature is above 45°C , forced cooling will be required)																		
	Storage Temperature	-20°C ~ 65°C																		
	Humidity	0 ~ 90% RH (non-condensing)																		
	Vibration	9.80665 m/s ² (1 G) less than 20 Hz, 5.88 m/s ² (0.6 G) 20 to 50 Hz																		
	IP Rating	IP20																		
	Power System	TN System ³																		
	Approvals	IEC/EN 61800-5-1, UL 508C, C-tick																		

Footnote:

¹ Rated rotation speed: When full load, speed ratio is defined as the minimum speed (the motor will not pause).

² When command is rated rotation speed, the speed fluctuation rate is defined as: (Empty load rotation speed - Full load rotation speed) / Rated rotation speed

³ TN system: A power distribution system having one point directly earthed, the exposed conductive parts of the installation being connected to that point by a protective earth conductor.



Specifications of ASDA-A2-E_400V Series

ASDA-A2-E Series		400W	750W	1kW	1.5kW	2kW	3kW	4.5kW	5.5kW	7.5kW			
		04	07	10	15	20	30	45	55	75			
Power Supply	Input Voltage	24V _{DC} , ±10%											
	Input Current	0.43A				1.18A			1.66A				
	Input Power	10.32W				28.2W			39.85W				
Main Circuit Power	Permissible Voltage Range	Three-phase, 380~480V _{AC} , ±10%											
	Input Current Unit: Arms	1.40	2.35	3.02	4.24	5.65	8.01	11.9	14.1	17.27			
	Continuous Output Current Unit: Arms	2.0	3.35	3.52	5.02	6.66	11.9	20	22.37	30			
Cooling Method		Fan Cooling											
Encoder Resolution (Servo Drive Resolution)		Incremental type: 20-bit ; Absolute type: 17-bit											
Control of Main Circuit		SVPWM (Space Vector Pulse Width Modulation) Control											
Tuning Modes		Auto / Manual											
Dynamic Brake		Built-in						no					
Position Control Mode (CSP)	Command Source	DS402 object											
	Smoothing Strategy	Low-pass and P-curve filter											
	Electronic Gear	Electronic gear N/M multiple N: 1 ~ 32767, M: 1 : 32767 (1/50 < N/M < 25600)											
	Torque Limit Operation	DS402 object											
Feed Forward Compensation		Internal parameters											
Speed Control Mode (CSV)	Speed Control Range ¹	1:5000						1:3000					
	Command Source	DS402 object											
	Smoothing Strategy	Low-pass and S-curve filter											
Torque Control Mode (CST)	Torque Limit Operation	Set by parameters											
	Frequency Response Characteristic	Maximum 1 kHz											
	Speed Accuracy (at rated rotation speed) ²	0.01 % or less at 0 to 100 % load fluctuation 0.01 % or less at 0°C to 50°C ambient temperature fluctuation 0.01 % or less at ±10 % power fluctuation											
Digital Inputs/Outputs	Speed Limit Operation	Via analog input											
	Inputs	Servo on, Reset, Gain switching, Zero speed CLAMP, Command input reverse control, Command triggered, Speed/Torque limit enabled, Position command selection, Motor stop, Speed position selection, Position / Speed mode switching, Speed / Torque mode switching, Torque / Position mode switching, Emergency stop, Forward / Reverse inhibit limit, Reference "Home" sensor, Forward / Reverse operation torque limit, Move to "Home", Electronic Cam (E-Cam), Forward / Reverse JOG input, Event trigger PR command, Electronic gear ratio (Numerator) selection Encoder signal output (A, B, Z Line Driver and Z Open Collector)											
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Protective Functions		Overcurrent, Overvoltage, Undervoltage, Motor overheated, Regeneration error, Overload, Overspeed, Abnormal pulse control command, Excessive deviation, Encoder error, Adjustment error, Emergency stop activated, Reverse/Forward limit switch error, Position excessive deviation of full-close control loop, Serial communication error, Input power phase loss, Serial communication time out, short circuit protection of U, V, W, and CN1, CN2, CN3 terminals											
Communication Interface		USB / EtherCAT											
Environment	Installation Site	Indoor location (free from direct sunlight), no corrosive liquid and gas (far away from oil mist, flammable gas, dust)											
	Altitude	Latitude 1000 m or lower above sea level											
	Atmospheric Pressure	86 kPa ~ 106 kPa											
	Operating Temperature	0°C ~ 55°C (If operating temperature is above 45°C , forced cooling will be required)											
	Storage Temperature	-20°C ~ 65°C											
	Humidity	0 ~ 90% RH (non-condensing)											
	Vibration	9.80665m/s ² (1 G) less than 20Hz, 5.88 m/s ² (0.6G) 20 to 50Hz											
	IP Rating	IP20											
Power System	Power System	TN System ³											
	Approvals	IEC/EN 61800-5-1, UL 508C, C-tick											

Footnote:

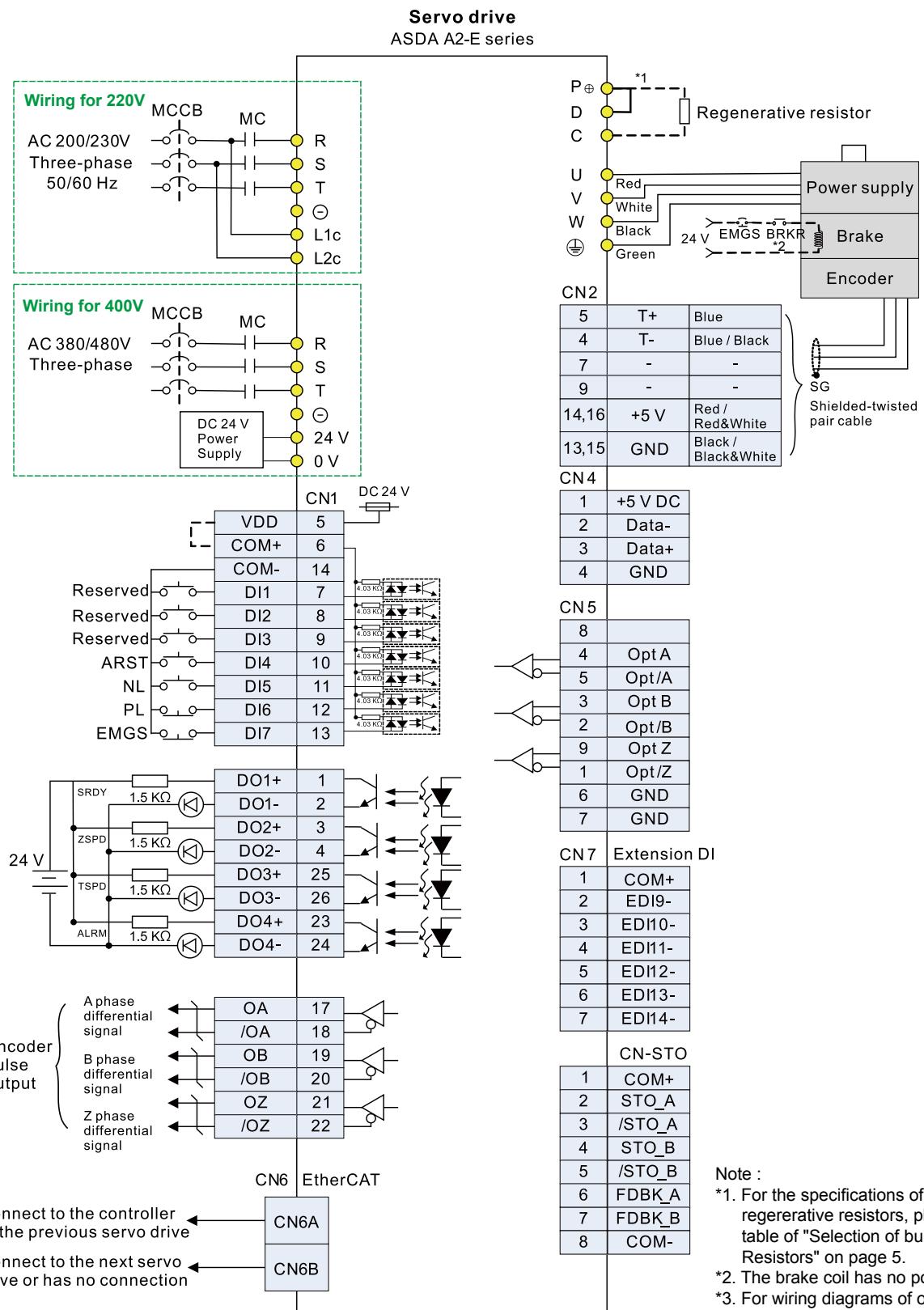
*1 Rated rotation speed: When full load, speed ratio is defined as the minimum speed (the motor will not pause).

*2 When command is rated rotation speed, the speed fluctuation rate is defined as: (Empty load rotation speed – Full load rotation speed) / Rated rotation speed

*3 TN system: A power distribution system having one point directly earthed, the exposed conductive parts of the installation being connected to that point by a protective earth conductor.



EtherCAT Communication Mode



Communication Specifications

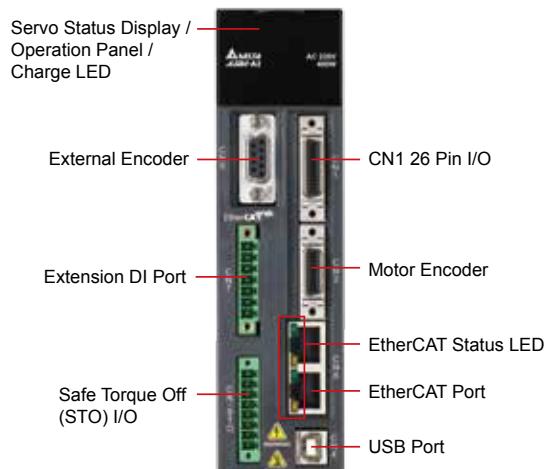
Physical Layer	IEEE802.3u (100 BASE-TX)
Data Link Layer	APRD, FPRD, BRD, LRD, APWR, FPWR, BWR, LWR, ARMW, FRMW, APRW, FPRW, BRW, LRW
Device Profile (CiA402)	Homing Mode, Profile Position Mode, Profile Velocity Mode, Profile Torque Mode, Interpolated Position Mode, Cyclic Syn. Position Mode, Cyclic Syn. Velocity Mode, Cyclic Syn. Torque Mode, Touch Probe Function, Torque Limit Function
Process Data Size	Tx: 8 Object (32 byte, Max.); Rx: 8 Object (32 byte, Max.) Dynamic Mapping supported.
Bus Clock	DC cycle with min. 250 us*
LED Indicator	EtherCAT Link/Activity Indicator (L/A) x 2 EtherCAT RUN Indicator (RUN) x 1 EtherCAT ERROR Indicator (ERR) x 1

* This function will be available in a new version soon to come.

Selection of Built-in Regenerative Resistors

220V Series									
Servo Drive (kW)	100W	200W	400W	750W	1.0kW	1.5kW	2.0kW	3.0kW	
Specification of Built-in Regenerative Resistor	NA	NA	40W 40 ohm	60W 40 ohm	60W 40 ohm	60W 40 ohm	100W 20 ohm	100W 20 ohm	
400V Series									
Servo Drive (kW)	400W	750W	1.0kW	1.5kW	2.0kW	3.0kW	4.5kW	5.5kW	7.5kW
Specification of Built-in Regenerative Resistor	40W 80 ohm	40W 80 ohm	40W 80 ohm	40W 80 ohm	NA	NA	NA	NA	NA

Part Names and Functions Ordering Information



ASD - A2 - 04 21 - E
 Series: A2
 Product Name: AC Servo Drive
 EtherCAT model
 Input Voltage and Phase
 21: 220V 1-phase / 3-phase
 23: 220V 3-phase
 43: 400V 3-phase

Rated Output Power
 01: 100W 15: 1.5kW
 02: 200W 20: 2kW
 04: 400W 30: 3kW
 07: 750W 45: 4.5kW
 10: 1kW 55: 5.5kW

Accessories for ASDA-A2-E

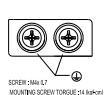
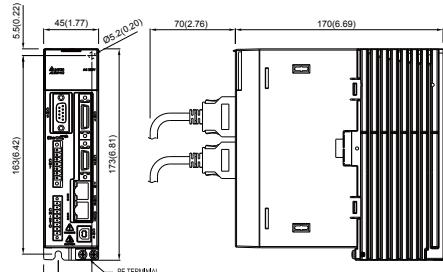


Note :
For other accessories, please refer to Delta's ASDA-A2 product catalogue.

Dimensions

► 220 V Series

100W / 200W / 400W

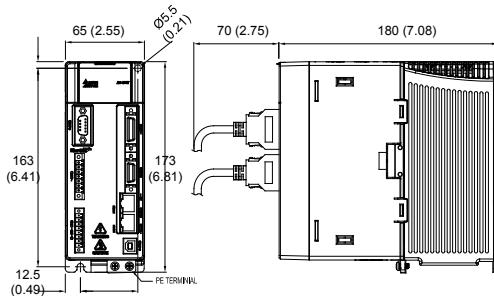


Weight 1.5 (3.3)

Weight

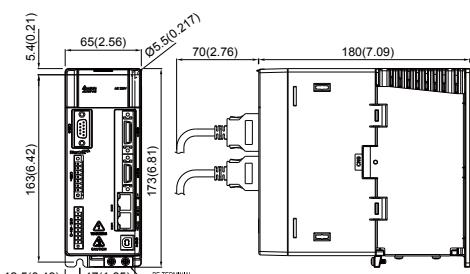
► 400 V Series

400W / 750W / 1kW / 1.5kW



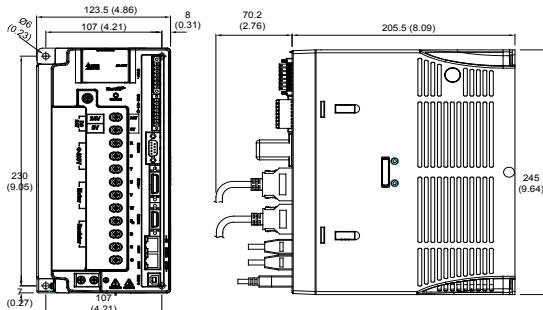
Weight 2.0 (4.4)

750W / 1kW / 1.5kW



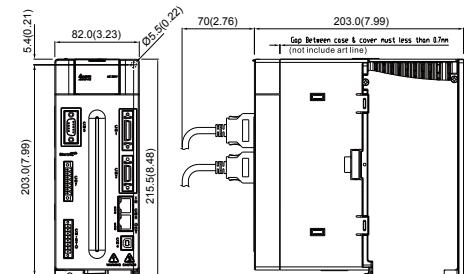
Weight 2.0 (4.4)

2kW / 3kW / 4.5kW / 5.5kW



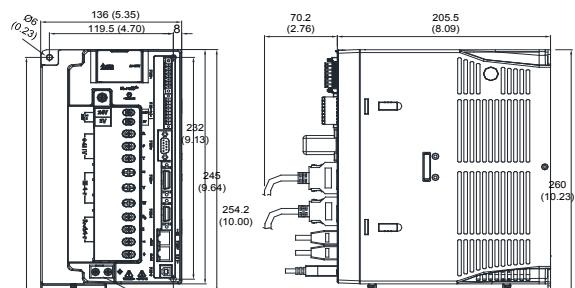
Weight 4.6 (10.1)

2kW / 3kW



Weight 2.89 (6.36)

7.5kW



Weight 5.5 (12.1)

Footnote:

- Dimensions are in millimeters (inches); Weights are in kilograms (kg) and pounds (lbs)
- Dimensions and weights of the servo drive may be revised without prior notice.



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*We reserve the right to change the information in this catalogue without prior notice.