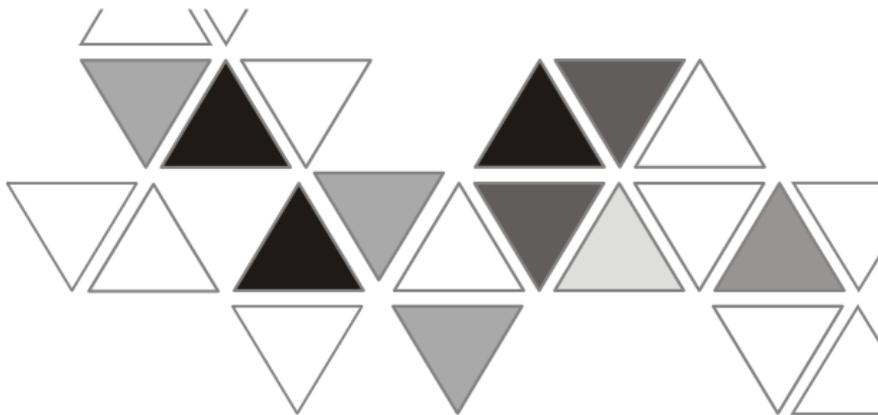


2009-06-18



5011669401-PM01



DVP-PM

INSTRUCTION SHEET

安裝說明 安装说明

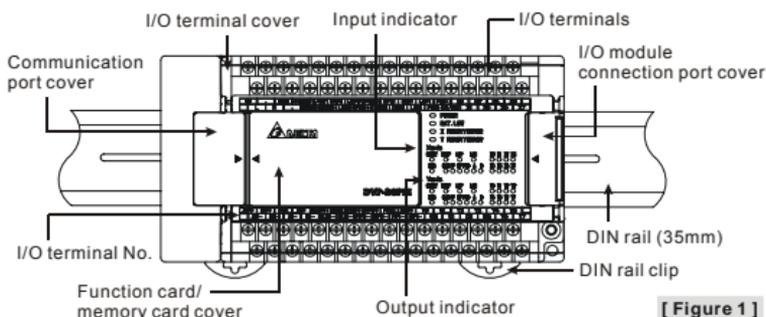
- ▲ *High-Speed Position, 2-Axis Linear/ Arc Interpolation, Multi-Functional Programmable Logic Controller*
- ▲ 高速定位·雙軸線性及圓弧補間·多功能可程式控制器
- ▲ 高速定位·双轴线性及圆弧补间·多功能可编程控制器



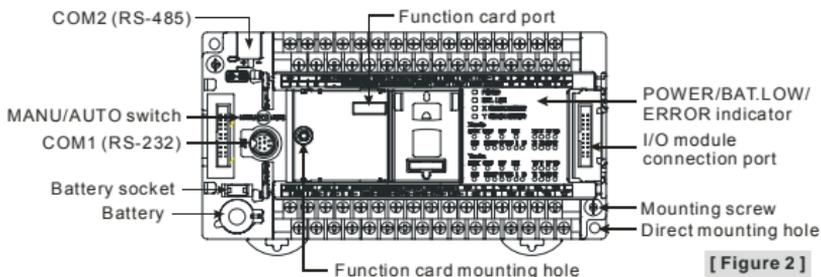
<http://www.delta.com.tw/industrialautomation>

- ✓ This instruction sheet only provides information on electrical specification, functions, wiring. For detailed information on programming and instructions, please refer to “DVP-PM Application Manual: Programming”. For more information about the optional peripherals, please see individual product instruction sheet or “DVP-PLC Application Manual: Special I/O Modules”.
- ✓ DVP-PM is an OPEN TYPE device and therefore should be installed in an enclosure free of airborne dust, humidity, electric shock and vibration. The enclosure should prevent non-maintenance staff from operating the device (e.g. key or specific tools are required for operating the enclosure) in case danger and damage on the device may occur.
- ✓ Do NOT connect the AC main circuit power supply to any of the input/output terminals, or it may damage the PLC. Check all the wiring prior to power up. To prevent any electromagnetic noise, make sure the PLC is properly grounded ⚡. Do NOT touch terminals when power on.

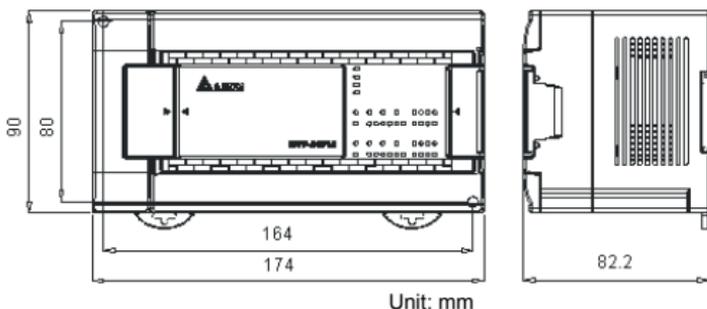
■ Product Profile & Dimension



[Figure 1]



[Figure 2]



[Figure 3]

■ Electrical Specifications

| DVP-PM | |
|----------------------|-----------------------------------------|
| Power supply voltage | 100 ~ 240VAC (-15% ~ 10%), 50/60Hz ± 5% |
| Fuse capacity | 2A/250VAC |
| Power consumption | 60VA |

| DVP-PM | |
|--------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| DC24V current output | 500mA |
| Power protection | DC24V; output short-circuited |
| Withstand voltage | 1,500VAC (Primary-secondary); 1,500VAC (Primary-PE); 500VAC (Secondary-PE) |
| Insulation impedance | > 5MΩ (all I/O point-to-ground 500VDC) |
| Noise immunity | ESD: 8KV Air Discharge, EFT: Power Line: 2KV, Digital I/O: 1KV, Analog & Communication I/O: 250V |
| Grounding | The diameter of grounding wire shall not be less than that of L, N terminal of the power. (When many PLCs are in use at the same time, please make sure every PLC is properly grounded.) |
| Operation/storage | Operation: 0°C ~ 55°C (temperature), 50 ~ 95% (humidity), pollution degree 2 Storage: -25°C ~ 70°C (temperature), 5 ~ 95% (humidity) |
| Vibration/shock immunity | International standards: IEC61131-2, IEC 68-2-6 (TEST Fc)/IEC61131-2 & IEC 68-2-27 (TEST Ea) |
| Weight (g) | 478/688 |

| Input Point | | | | | | |
|--------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------|------------|-------|-------|-----|
| Terminal | Description | Response char. | Max. input | | Model | |
| | | | Cur. | Volt | 20D | 20M |
| START0 · START1 | Enabling input | 10ms | 6mA | 24V | ✓ | ✓ |
| STOP0 · STOP1 | Disabling input | 10ms | 6mA | 24V | ✓ | ✓ |
| LSP0 / LSN0 · LSP1 / LSN1 | Right / left limit input | 10ms | 6mA | 24V | ✓ | ✓ |
| X1 / X2 (for Z axis) | Right / left limit input (COM) | 10ms | 6mA | 24V | - | ✓ |
| A0+ · A0- · A1+ · A1- (Y and Z axis share) | MPG A-phase pulse input +,- (differential signal input) | 200kHz | 15mA | 5~24V | ✓ | ✓ |
| B0+ · B0- · B1+ · B1- (Y and Z axis share) | MPG B-phase pulse input +,- (differential signal input) | 200kHz | 15mA | 5~24V | ✓ | ✓ |
| PG0+ · PG0- · PG1+ · PG1- | Zero point signal input +,- (differential signal input) | 200kHz | 15mA | 5~24V | ✓ | ✓ |
| X3 (for Z axis) | Zero point signal input (COM) | 10ms | 6mA | 24V | - | ✓ |
| DOG0 · DOG1 | There are 2 variations according to different operation modes: 1. DOG signal when zero return 2. Inserting enabling signal at 1-seg. or 2-seg. speed | 1ms | 6mA | 24V | ✓ | ✓ |
| X0 (for Z axis) | Same as DOG0 · DOG1 (COM) | 10ms | 6mA | 24V | - | ✓ |

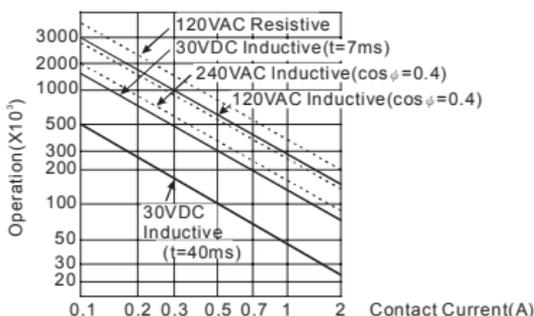
| Digital Input Point | | | |
|----------------------------------------------|---------------------------------------------|-----------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Item \ Spec | 24VDC signal common port input | | Note |
| | Low speed | High speed (200kHz) ^{#1} | |
| Input wiring type | Change wiring from S/S to SINK or SOURCE | | #1: Input point A, B, PG is high-speed input; other input point is low-speed input. #2: Input point X0 ~ X7 can conduct 10 ~ 60ms digital filter adjustment. |
| Input indicator | LED display; light on = ON, light off = OFF | | |
| Input voltage | - | | |
| Action level | Off→On: 20us, On→Off: 30us | | |
| Response time / noise immunity ^{#2} | 10ms | 0.5us | |

| Output Point | | | | | |
|------------------------------|-------------------------------------------------------------------------------------------------|----------------|--------------------|-------|-----|
| Terminal | Description | Response char. | Max. input current | Model | |
| | | | | 20D | 20M |
| CLR0+ · LR0- · CLR1+ · CLR1- | Clearing signals (by the error counter in Servo drive) | 10ms | 20mA | ✓ | ✓ |
| Y2 (for Z axis) | Same as Clearing signals (COM) | 10ms | 30mA | - | ✓ |
| FP0+ · FP0- · FP1+ · FP1- | Forward/reverse running mode: Forward pulse output Pulse direction: towards pulse output end | 500kHz | 40mA | ✓ | ✓ |
| FP2+ · FP2- | A, B phase: A-phase output (FP2+ · FP2- are for Z axis pulse output) | | | - | ✓ |
| RP0+ · RP0- · RP1+ · RP1- | Forward/reverse running mode: Reverse pulse output Pulse direction: towards output end | 500kHz | 40mA | ✓ | ✓ |
| RP2+ · RP2- | A, B phase: B-phase output (RP2+ · RP2- are for Z axis pulse output) | | | - | ✓ |

| Digital Input Point | | | | |
|------------------------|-----------|---------------------------------------------|------------|------------------------------------|
| Item | Spec | Single common port transistor output #1 | | Single common port relay output #1 |
| | | Low speed | High speed | |
| Maximum frequency | | 10kHz | 200kHz | For load ON/OFF control |
| Output indicator | | LED display; light on = ON, light off = OFF | | |
| Minimum load | | - | | 2mA/DC power supply |
| Working voltage | | 5 ~ 30VDC | | < 250VAC, 30VDC |
| Insulation | | Photo coupler isolation | | Electromagnetic isolation |
| Maximum load | Resistive | 0.5A/1 point (4A/COM) | | 2A/1 point (5A/COM) |
| | Inductive | 12W (24VDC) | | #2 |
| | Lamp | 2W(24VDC) | | 20WDC/100WAC |
| Max. output delay time | Off→On | 20us | 0.2us | 10ms |
| | On→Off | 30us | | |
| Over-current | | N/A | | |

#1: For DVP20PM00D, Y0 ~ Y7 are relay output terminals. For DVP20PM00M, FP2+ and PF2- are high speed transistor output terminals, Y2 and Y3 are low speed transistor output terminals and Y4~Y7 are relay output terminals.

#2: Life curves

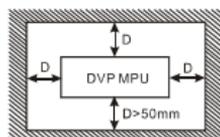


[Figure 4]

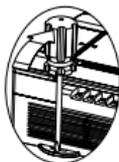
■ Installation

Please install the PLC in an enclosure with sufficient space around it to allow heat dissipation, as shown in the figure.

- **Direct Mounting:** Please use M4 screw according to the dimension of the product.

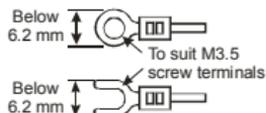


- DIN Rail Mounting:** When mounting the PLC to 35mm DIN rail, be sure to use the retaining clip to stop any side-to-side movement of the PLC and reduce the chance of wires being loose. The retaining clip is at the bottom of the PLC. To secure the PLC to DIN rail, pull down the clip, place it onto the rail and gently push it up. To remove the PLC, pull the retaining clip down with a flat screwdriver and gently remove the PLC from DIN rail, as shown in the figure.



■ Wiring

- Use O-type or Y-type terminal. See the figure in the right hand side for its specification. PLC terminal screws should be tightened to 9.50 kg-cm (8.25 in-lbs) and please use only 60/75°C copper conductor.
- DO NOT wire empty terminal. DO NOT place the input signal cable and output power cable in the same wiring circuit.
- DO NOT drop tiny metallic conductor into the PLC while screwing and wiring. Tear off the sticker on the heat dissipation hole for preventing alien substances from dropping in, to ensure normal heat dissipation of the PLC.



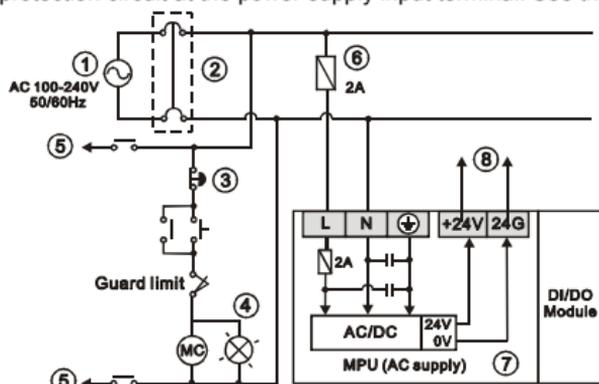
◆ Power Supply

The power input type for DVP-PM series is AC input. When operating the PLC, please note the following points:

- The input voltage should be current and its range should be 100 ~ 240VAC. The power should be connected to L and N terminals. Wiring AC110V or AC220V to +24V terminal or input terminal will result in serious damage on the PLC.
- The AC power input for PLC MPU and I/O modules should be ON or OFF at the same time.
- Use wires of 1.6mm (or longer) for the grounding of PLC MPU.
- The power shutdown of less than 10 ms will not affect the operation of the PLC. However, power shutdown time that is too long or the drop of power voltage will stop the operation of the PLC and all outputs will go OFF. When the power returns to normal status, the PLC will automatically resume operation. (Care should be taken on the latched auxiliary relays and registers inside the PLC when programming).
- The +24V output is rated at 0.5A from MPU. DO NOT connect other external power supplies to this terminal. Every input terminal requires 6 ~ 7mA to be driven; e.g. the 16-point input will require approximately 100mA. Therefore, +24V terminal cannot give output to the external load that is more than 400mA.

◆ Safety Wiring

In PLC control system, many devices are controlled at the same time and actions of any device could influence each other, i.e. breakdown of any device may cause the breakdown of the entire auto-control system and danger. Therefore, we suggest you wire a protection circuit at the power supply input terminal. See the figure below.



[Figure 5]

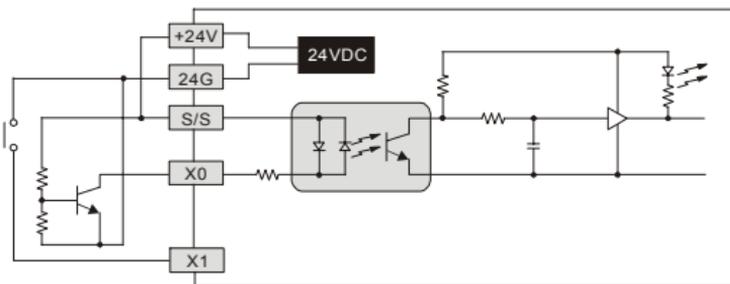
- | | |
|-------------------------------------------------------------------------------------------------------|----------------------------------|
| ① AC power supply: 100 ~ 240VAC, 50/60Hz | ② Breaker |
| ③ Emergency stop: This button cuts off the system power supply when accidental emergency takes place. | |
| ④ Power indicator | ⑤ AC power supply load |
| ⑥ Power supply circuit protection fuse (2A) | ⑦ DVP-PLC (main processing unit) |
| ⑧ DC power supply output: 24VDC, 500mA | |

◆ Input Point Wiring

There are 2 types of DC inputs, SINK and SOURCE. (See the example below. For detailed point configuration, please refer to the specification of each model.)

• DC Signal IN – SINK mode

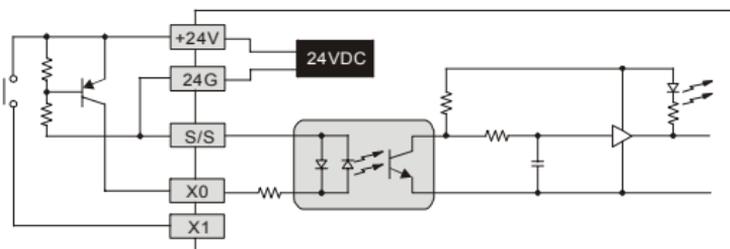
Input point loop equivalent circuit



[Figure 6]

• DC Signal IN – SOURCE mode

Input point loop equivalent circuit

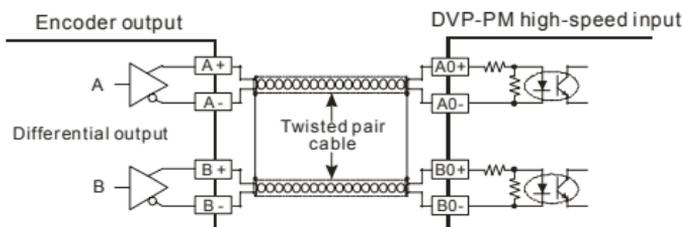


[Figure 7]

◆ Wiring of Differential Input

A0 ~ A1 and B0 ~ B1 of DVP-PM series are all DC5V ~ 24V high-speed input circuit and others are DC24V input. The working frequency of high-speed input circuit can reach up to 200kHz and is mainly for connecting to differential (double-wire) LINE DRIVER output circuit.

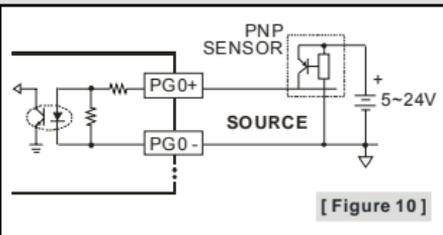
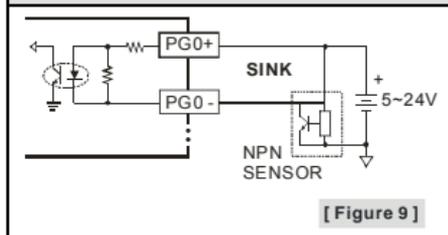
• Wiring in a high-speed, high-noise environment



[Figure 8]

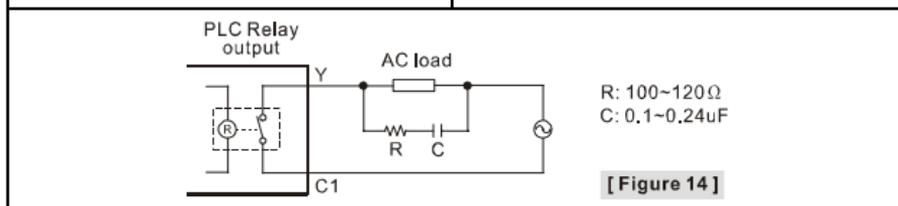
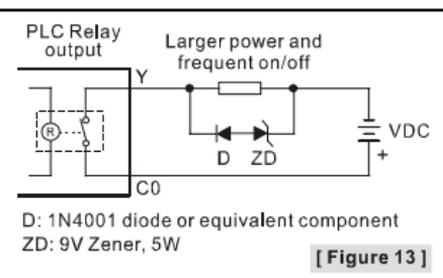
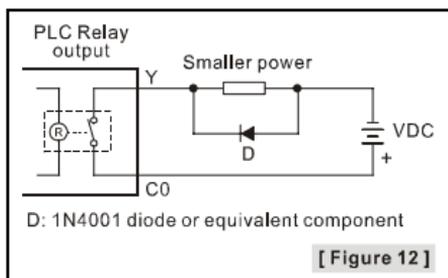
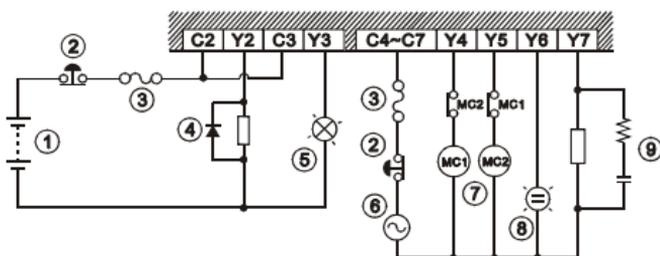
In a low-noise and low-frequency (less than 50kHz) environment, you may also use DC5~24V SINK/SOURCE input of a single port.

Wiring of DVP-PM DC5V ~ 24V



◆ Output Point Wiring

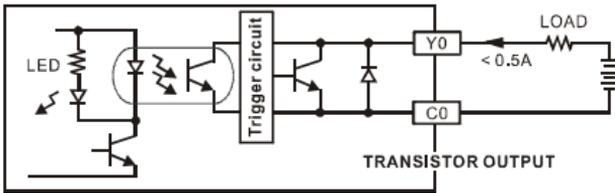
- Relay (R) contact circuit wiring



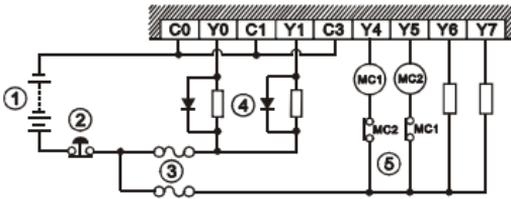
- ① DC power supply
- ② Emergency stop: Uses external switch
- ③ Fuse: Uses 5~10A fuse at the shared terminal of output contacts to protect the output circuit
- ④ Transient voltage suppressor: To extend the life span of contact.
 1. Diode suppression of DC load: Used when in smaller power (Figure 12)
 2. Diode + Zener suppression of DC load: Used when in larger power and frequent On/Off (Figure 13)
- ⑤ Incandescent light (resistive load)
- ⑥ AC power supply
- ⑦ Manually exclusive output: For example, Y4 and Y5 control the forward running and reverse running of the motor, forming an interlock for the external circuit, together with the PLC internal program, to ensure safe protection in case of any unexpected errors.
- ⑧ Neon indicator
- ⑨ Absorber: To reduce the interference on AC load (Figure 14)

• Transistor (T) contact circuit wiring

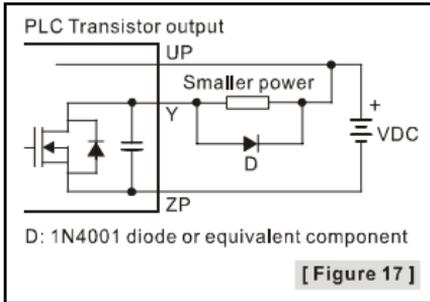
DVP-**-**-**-T



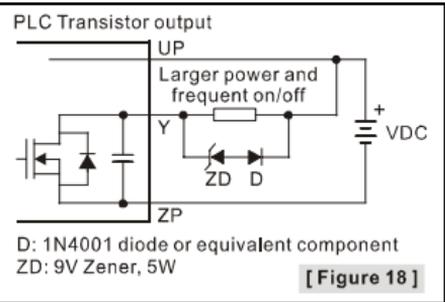
[Figure 15]



[Figure 16]



[Figure 17]



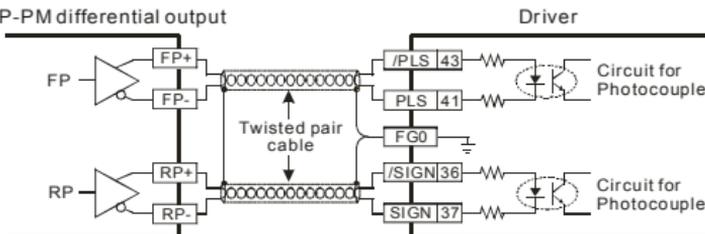
[Figure 18]

- ① DC power supply
- ② Emergency stop
- ③ Circuit protection fuse
- ④ The output of the transistor model is "open collector". If Y0/Y1 is set to pulse output, the output current has to be bigger than 0.1A to ensure normal operation of the model.
 - 1. Diode suppression: Used when in smaller power (Figure 18)
 - 2. Diode + Zener suppression: Used when in larger power and frequent On/Off (Figure 19)
- ⑤ Manually exclusive output: For example, Y4 and Y5 control the forward running and reverse running of the motor, forming an interlock for the external circuit, together with the PLC internal program, to ensure safe protection in case of any unexpected errors.

◆ Wiring of Differential Output

• DVP-PM differential output with ASDA-A & A+, ASDA-A2 series driver

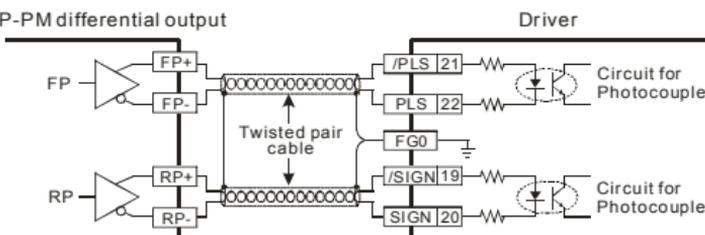
DVP-PM differential output



[Figure 19]

• DVP-PM differential output with ASDA-B series driver

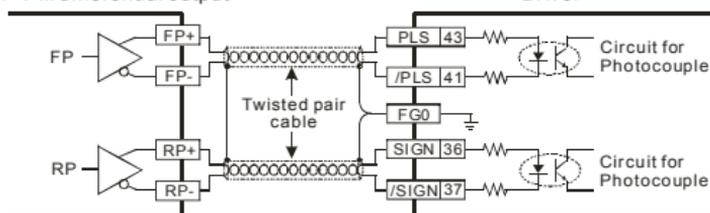
DVP-PM differential output



[Figure 20]

- DVP-PM differential output with ASDA-AB series driver

DVP-PM differential output



[Figure 21]

■ BAT.LOW indicator

BAT.LOW indicator will be on when the battery is in low voltage. When this happens, change the battery as soon as possible in case your program and data saved in the latched area will be lost.

After the power is switched off, the data in the latched area are stored in SRAM memory and its power is supplied by the battery. Therefore, when the battery is in low voltage and the power-off has been lasted for more than 1 minute, the data in the latched area will be lost. If you need to permanently save the data in the latched area in the program and device D, refer to "Flash ROM permanently saved and recover mechanism" as stated below.

Permanently saved mechanism

You can use WPLSoft (Options -> PLC<=>Flash) to indicate whether to permanently store the data in the latched area in Flash ROM memory (new indicated data will replace all data previously saved in the memory).

Recover mechanism

If the battery is in low voltage (before the power is switched off when the BAT.LOW indicator is on) and the power is off for more than 1 minute, PLC will automatically restore the data in the latched area in the program and device D of Flash ROM into SRAM memory next time when it is re-powered.

◆ Battery Life

| Temperature (°C) | -30 | 0 | 25 | 50 | 70 |
|------------------|-----|---|----|----|----|
| Life (year) | 10 | 9 | 8 | 6 | 5 |